# **Tournament Solutions**

#### and their Applications to Multiagent Decision-Making

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#### Multiagent Decision-Making

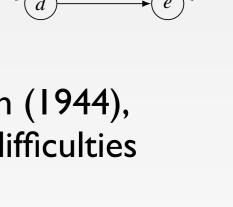
#### • Collective decision-making

- Social choice theory
- How to aggregate the possibly conflicting preferences of multiple agents?
- Adversarial decision-making
  - Theory of zero-sum games
  - Which strategy should be pursued when interacting with other agents?
- Coalitional decision-making
  - Cooperative game theory
  - Which coalitions of agents will form and how should they divide the proceeds of cooperations?



## The Trouble with Tournaments

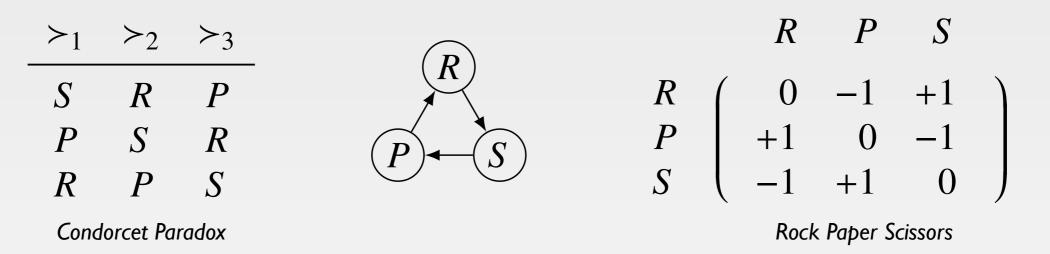
- Problem: Find "best" elements according to some binary dominance relation
  - Set of alternatives is finite
  - Dominance relation is asymmetric and complete
  - Maximal elements need not exist ("Condorcet paradox" in social choice theory)
  - According to game theorists von Neumann & Morgenstern (1944), cyclical dominations are "one of the most characteristic difficulties which a theory of these phenomena must face."
- Numerous applications
  - social choice theory, cooperative and non-cooperative game theory
    - also multi-criteria decision analysis, sports tournaments, psychometrics, biology, argumentation theory, webpage and journal ranking, etc.



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### Social Choice & Game Theory



- Theorem (McGarvey, 1953): Any asymmetric relation can be induced by majority rule.
  - When the number of voters is odd and individual preferences are strict, then any relation induced by majority rule is asymmetric and complete.
- Tournament games
  - Subclass of symmetric two-player zero-sum games
    - players may only win, lose, or draw
    - game ends in draw iff both players play the same action



# Terminology & Notation

- Finite set of alternatives A
- Asymmetric and complete dominance relation  $\succ \subseteq A \times A$
- Tournament T = (A, >)
- $\mathcal{T}(A)$ : Set of all tournaments on A
- Tournament solution S associates with each tournament T a nonempty subset of alternatives (the "winners" of T according to S)  $S : \mathcal{T}(A) \to \mathcal{P}(A) \setminus \emptyset$ 
  - stable with respect to tournament isomorphisms:  $S \circ \pi = \pi \circ S$
  - selects maximal element whenever one exists:  $max(T) \subseteq S(T)$
- $S(B) = S(T|_B) = S((B, \geq|_B))$  for  $B \subseteq A$
- Dominion  $D_{(A,\succ)}(a) = \{ b \in A \mid a \succ b \}$
- Dominators  $\overline{D}_{(A,\succ)}(a) = \{ b \in A \mid b \succ a \}$

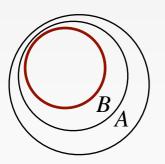


## **Desirable Properties**

- Monotonicity (MON)
  - An alternative remains in the choice set when its dominion is extended.

 $a \in S(T) \Rightarrow a \in S(T') \quad \forall T = (A, \succ), T' = (A, \succ'), a \in A:$  $T|_{A \setminus \{a\}} = T'|_{A \setminus \{a\}} \land D_T(a) \subseteq D_{T'}(a)$ 

- Strong Superset Property (SSP)
  - The choice set is invariant under removal of unchosen alternatives.



 $S(B) = S(A) \quad \forall T = (A, \succ), B \subseteq A:$  $S(A) \subseteq B$ 

• Further properties: idempotency (IDE), weak superset property (WSP), independence of unchosen alternatives (IUA), composition-consistency (COM), irregularity (IRR)



## **Tournament Solution Hierarchy**

(B., 2008)

via qualified subsets	via stable sets
Banks set (Banks, 1985) Minimal covering s	
	<b>Tournament equilibrium set</b> (Schwartz, 1990)
Copeland set (Zermelo, 1929; Copeland, 1951)	
Uncovered set (	(Fishburn, 1977; Miller, 1980) extending set
Со	ndorcet non-losers (Condorcet, 1785)
Bipartisan set (Laffond et al., 1993)	
- ````````````````````````````````````	<b>Top cycle</b> (Good, 1971; Smith, 1973)
later set (Slater 1961)	Markov set (Daniels, 1969)

- Infinite hierarchy of tournament solutions
  - improve understanding of tournament solutions and their relationships
  - unify proofs of properties and inclusions
  - define new tournament solutions, e.g., minimal extending set



#### The Top Cycle

(Good, 1971; Smith, 1973)

- A dominating set is a set of alternatives such that every alternative in the set dominates every outside alternative.
  - The set of all dominating sets is totally ordered by set inclusion.
  - Every tournament contains a unique minimal dominating set.
- The minimal dominating set is called the top cycle (TC).
  - also known as GETCHA or Smith set
- Theorem (Bordes, 1976): The top cycle is the smallest tournament solution satisfying β<sup>+</sup>.
  - It also satisfies WSP, SSP, MON, IUA.
- How can we efficiently compute the top cycle?

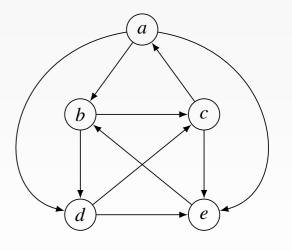




### TC (linear-time algorithm)

- Algorithm for computing TC<sub>a</sub>, the minimal dominating set containing a given alternative a
  - Initialize working set B with {a} and then iteratively add all alternatives that dominate an alternative in B until no more such alternatives can be found.
  - Computing  $TC_a$  for every alternative a and then choosing the smallest set yields an  $O(n^3)$  algorithm.
- Alternatives with maximal degree (the Copeland winners) are always contained in TC (and linear-time computable).

**procedure** 
$$TC(A, >)$$
  
 $B \leftarrow C \leftarrow CO(A, >)$   
**loop**  
 $C \leftarrow \bigcup_{a \in C} \overline{D}_{A \setminus B}(a)$   
**if**  $C = \emptyset$  **then return**  $B$  **end if**  
 $B \leftarrow B \cup C$   
**end loop**





### More on the Top Cycle

- Theorem (Deb, 1977): The top cycle consists precisely of the maximal elements of the asymmetric part of the transitive closure of the dominance relation.
  - Alternative linear-time algorithm using Kosaraju's or Tarjan's algorithm for finding strongly connected components
- There is a first-order expression for membership in TC (B., Fischer, & Harrenstein; 2009):  $TC(x) \leftrightarrow \forall y \forall z (\forall v (z \ge^3 v \rightarrow z \ge^2 v) \land z \ge^2 x \rightarrow z \ge^2 y)$ 
  - Computing TC is in AC<sup>0</sup>
- The top cycle is very large.
  - In fact, it is so large that it may contain Pareto-dominated alternatives when used as a social choice function.



#### The Uncovered Set

(Fishburn, 1977; Miller, 1980)

- Covering relation: a covers b if  $D(b) \subset D(a)$ .
  - The covering relation is a transitive subrelation of the dominance relation.
- The uncovered set (UC) consists of all uncovered alternatives.
  - UC contains the maximal element of inclusion-maximal subsets that admit a maximal element.
- Example
  - ► UC = {a,b,c,d}
- Theorem (Moulin, 1986): The uncovered set is the smallest tournament solution satisfying γ.
  - It also satisfies WSP, MON, and COM and is contained in TC.



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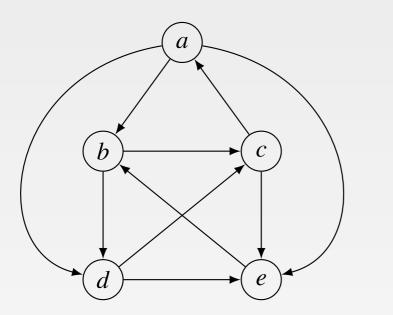
#### UC algorithm

- Straightforward n<sup>3</sup> algorithm
- Equivalent characterization of UC
  - UC consists precisely of those alternatives that reach every other alternative on a domination path of length at most two. (Shepsle & Weingast, 1984).
- Algorithm via matrix multiplication
  - Fastest known matrix multiplication algorithm (Coppersmith & Winograd, 1990): O(n<sup>2.38</sup>)
  - Matrix multiplication is believed to be feasible in linear time  $(O(n^2))$ .

procedure UC(A, >)for all  $i, j \in A$  do if  $i > j \lor i = j$  then  $m_{ij} \leftarrow 1$ else  $m_{ij} \leftarrow 0$  end if end for  $M \leftarrow (m_{ij})_{i,j \in A}$  $U \leftarrow (u_{ij})_{i,j \in A} \leftarrow M^2 + M$  $B \leftarrow \{i \in A \mid \forall j \in A : u_{ij} \neq 0\}$ return B



#### UC algorithm (example)



procedure UC(A, >)for all  $i, j \in A$  do if  $i > j \lor i = j$  then  $m_{ij} \leftarrow 1$ else  $m_{ij} \leftarrow 0$  end if end for  $M \leftarrow (m_{ij})_{i,j \in A}$  $U \leftarrow (u_{ij})_{i,j \in A} \leftarrow M^2 + M$  $B \leftarrow \{i \in A \mid \forall j \in A : u_{ij} \neq 0\}$ return B



### The Minimal Covering Set

(Dutta, 1988)

- A covering set is a set of alternatives B such that a∉UC(B∪{a}) for all alternatives a∉B.
  - Theorem (Dutta, 1988): Every tournament contains a unique minimal covering set (MC).
- Example
  - Covering sets: {a,b,c,d,e}, {a,b,c,d}, and {a,b,c}
  - $MC = \{a,b,c\}$

Bhaskar Dutta

- Theorem (Dutta, 1988): The minimal covering set is the smallest tournament solution satisfying SSP and  $\gamma^*$ .
  - It also satisfies WSP, MON, IUA, and COM and is contained in UC.
  - MC is equivalent to a game-theoretic concept proposed by Shapley in 1953 (Duggan & Le Breton, 1996)



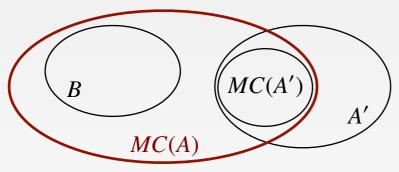
## MC (complexity)

- No obvious reason why computing MC should be in NP
  - Verifying whether a set is a covering set is easy, verifying minimality is not.
  - Checking whether a set is MC and checking whether an alternative is contained in MC is in coNP.
    - A covering set is *not* minimal if there exists a proper covering subset.
- Straightforward iterative algorithms do not work
  - start with entire set and remove alternatives
    - there may be no covering sets in between entire set and MC
  - start with singleton and add alternatives
    - unclear which of the alternatives that are not covered by the current working set should be included



## MC (algorithm)

- Three insights needed for polynomial-time algorithm
  - Lemma: If  $B \subseteq MC(A)$  and  $A' = \bigcup_{a \in A \setminus B} (UC(B \cup \{a\}) \cap \{a\})$ then  $MC(A') \subseteq MC(A)$ .



- For every proper subset of MC, the lemma tells us how to find another disjoint and non-empty subset of MC.
- Lemma (Laffond, Laslier, & Le Breton; 1993): Every tournament game contains a unique Nash equilibrium, the support of which (the so-called bipartisan set BP) is contained in MC.
- The bipartisan set can be computed via linear programming.

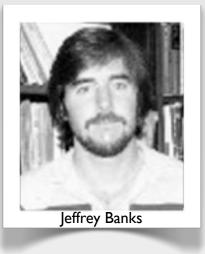


#### MC (algorithm, ctd.)

 Theorem (B. and Fischer, 2008): The minimal covering set can be computed in polynomial time.

procedure MC(A, >)  $B \leftarrow BP(A, >)$ loop  $A' \leftarrow \bigcup_{a \in A \setminus B} (UC(B \cup \{a\}) \cap \{a\})$ if  $A' = \emptyset$  then return B end if  $B \leftarrow B \cup BP(A', >)$ end loop **procedure** BP(A, >) **for all**  $i, j \in A$  **do if** i > j **then**  $m_{ij} \leftarrow 1$  **else if** j > i **then**  $m_{ij} \leftarrow -1$  **else**  $m_{ij} \leftarrow 0$  **end if end for**   $s \in \{s \in \mathbb{R}^n \mid \sum_{j \in A} s_j \cdot m_{ij} \le 0 \quad \forall i \in A$   $\sum_{j \in A} s_j = 1$   $s_j \ge 0 \qquad \forall j \in A\}$   $B \leftarrow \{a \in A \mid s_a > 0\}$ **return** B

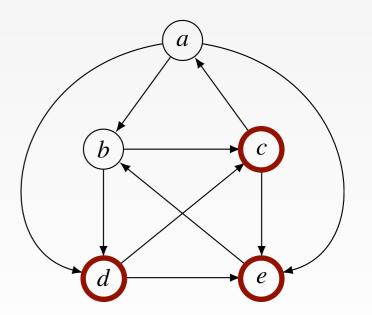




#### Banks set

(Banks, 1985)

- The Banks set (BA) consists of the maximal elements of maximal transitive subsets.
- Theorem (B., 2008): The Banks set is the smallest tournament solution satisfying strong retentiveness.
  - It also satisfies WSP, MON, IRR, COM, and is contained in UC.
- Random alternatives in BA can be found efficiently.
  - ► BA = {a,b,c,d}
- Theorem (Woeginger, 2003): Deciding whether a given alternative is contained in BA is NP-complete.

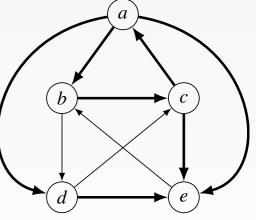


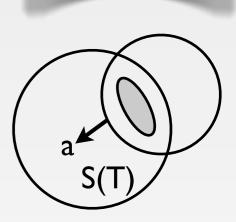


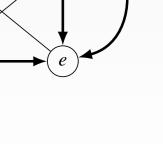
#### Tournament Equilibrium Set

(Schwartz, 1990)

- A tournament solution S is retentive if  $S(\overline{D}(a)) \subseteq S(T)$  for all  $a \in S(T)$  and all tournaments T.
  - Idea: No alternative in the choice set should be "properly" dominated by an outside alternative.
- TEQ is the smallest tournament solution satisfying retentiveness.
  - Characterization relies on Schwartz's conjecture.
  - TEQ satisfies IRR and COM and is contained in BA.
- Example: TEQ = {a,b,c}





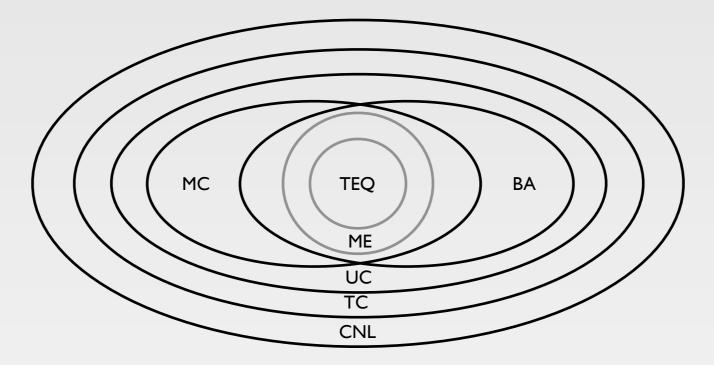




#### The Mystery of TEQ

- Theorem (Laffond et al., 1993; Houy, 2009): The following statements are equivalent:
  - Schwartz's conjecture
  - TEQ satisfies WSP.
  - TEQ satisfies SSP.
  - TEQ satisfies MON.
  - TEQ satisfies IUA.
- Furthermore, these statements imply that TEQ is contained in MC.
- All or nothing: Either TEQ is a most appealing tournament solution or it is severely flawed.
- Theorem (B., Fischer, Harrenstein, Mair; 2010): Deciding whether an alternative is contained in TEQ is NP-hard.
  - The best known upper bound is PSPACE!





			1	MON	WSP	SSP	IDE	IUA	сом	IRR	EFFICIENTLY COMPUTABLE
$S_{\mathcal{M}_2}$	CNL	(Condorcet, 1785)		$\checkmark$	$\checkmark$	-	-	$\checkmark$	-	-	$\checkmark$
•			Ι	$\checkmark$	$\checkmark$	-	-	-	-	-	$\checkmark$
$S_{\mathcal{M}}$	UC	(Fishburn, 1977; Miller, 1980)	I	$\checkmark$	$\checkmark$	-	-	-	$\checkmark$	-	$\checkmark$
$S_{\mathcal{M}^*}$	BA	(Banks, 1985)	Ι	$\checkmark$	$\checkmark$	-	-	-	$\checkmark$	$\checkmark$	NP-hard
$\widehat{S}_{\mathcal{M}_2}$	ТС	(Good, 1971; Smith, 1973)	Ι	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-	-	$\checkmark$
• •			Ι	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-	-	$\checkmark$
$\widehat{S}_{\mathcal{M}}$	MC	(Dutta, 1988)	I	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-	$\checkmark$
$\widehat{S}_{\mathcal{M}^*}$	ME	(Brandt, 2008)		$\checkmark$	NP-hard						
TEQ	TEQ	(Schwartz, 1990)		$\checkmark$	NP-hard						