

Sonar/Oredi

A Tool for Creation and Deployment of Organisation Models

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MATES'10

Agent vs. Organisation

Agents

- local autonomy
- intelligence:
goal-orientation, learning
- social awareness:
cooperation, competition

Problems

- bounded rationality:
sub-optimal solutions
- scaling problem for large agent
populations

Organisations

- global coherence
- organisational learning,
data mining
- teams

Solutions

- social structures:
roles, protocols, norms
- reduction of complexity:
interaction networks,
e.g. hierarchies

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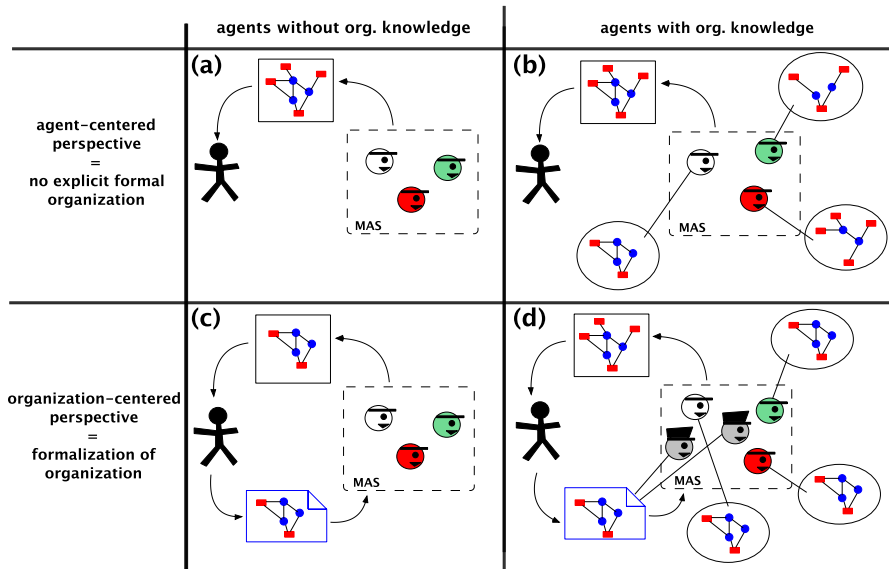
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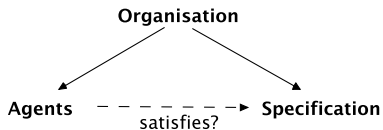
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Matrix: Organisation Awareness



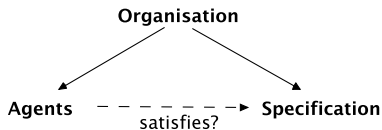
The Formal Organisation as an Artefact

Organisation considered as a Specification:

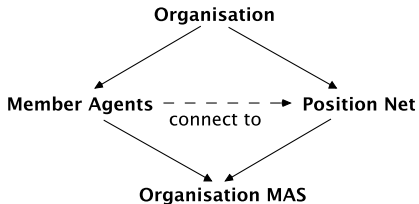


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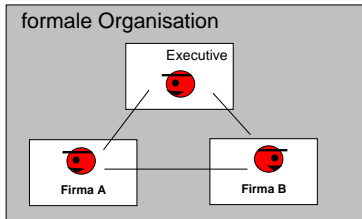


SONAR: Organisation considered as a Multi-Agent System:



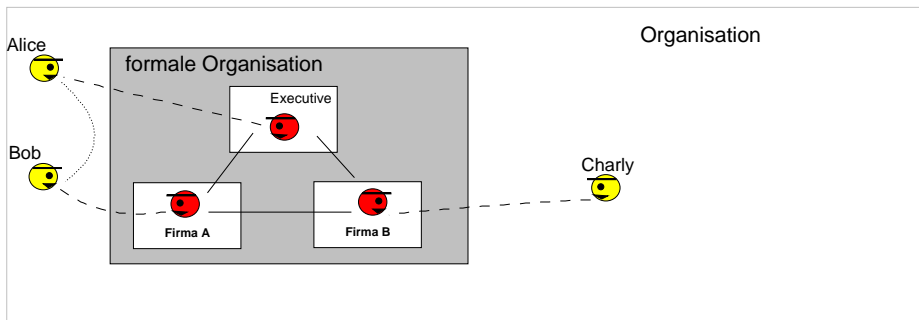
Formal vs. informal Organisation

SONAR: The organisation as a MAS.



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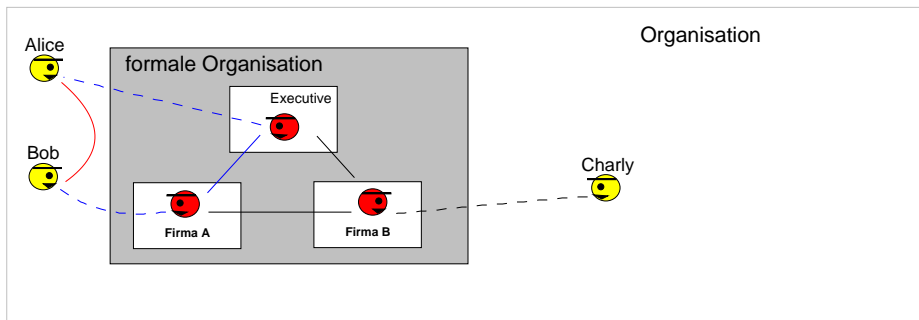


Membership:

An agent becomes a member of the organisation via binding to a position.

Formal vs. informal Organisation

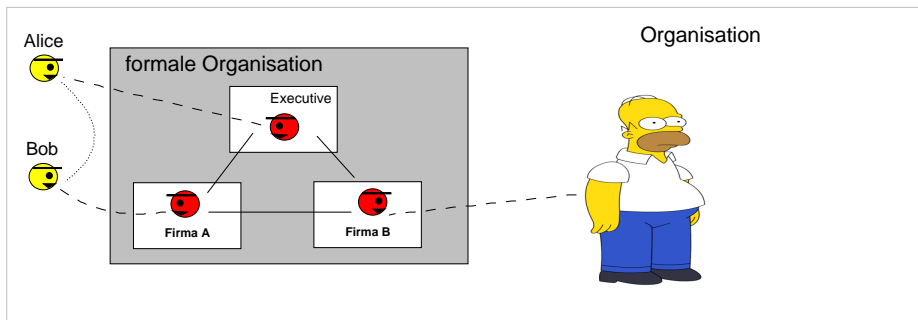
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inofficial vs. official communication

Formal vs. informal Organisation

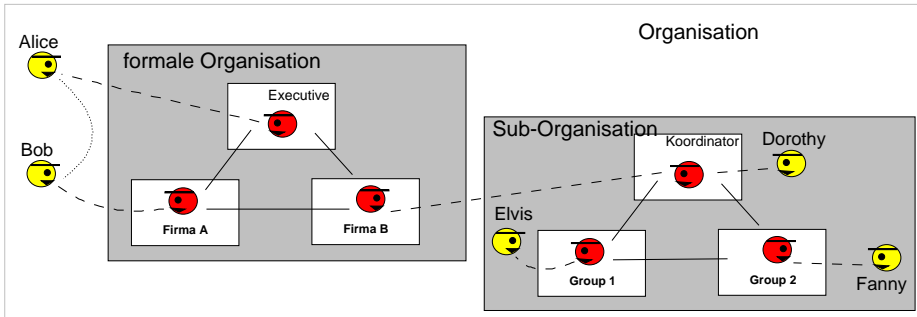
SONAR: The organisation as a MAS.



Hybrid Organisation: Artefacts + Humans

Formal vs. informal Organisation

SONAR: The organisation as a MAS.



Suborganisation, Holons

1 Sonar

- Static Aspects: Position Network, Roles, AIP
- Dynamic Aspects: Teamwork
- Theoretical Aspects

2 Mulan4Sonar

- Deployment of SONAR-Models
- The Organisation Agent
- The Position Agent

3 The Sonar/Oredi Compiler

- Middleware: Design Objectives
- The Mulan4Sonar Prototype
- Compilation as Graph Transformation

4 Conclusion

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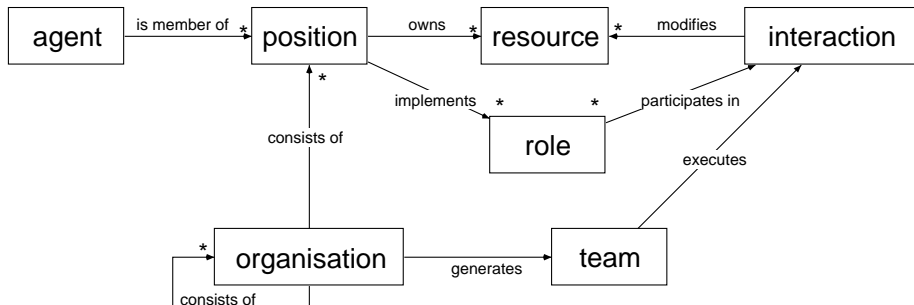
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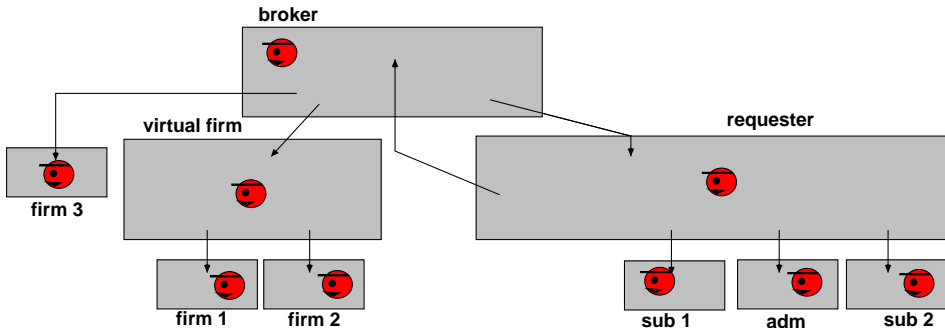
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Overview of Sonar Concepts

Basic SONAR concepts:

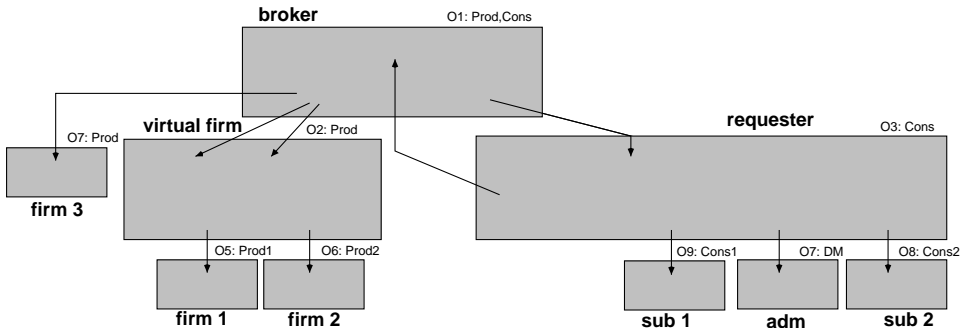


Static Aspects: Position Network, Roles, AIP



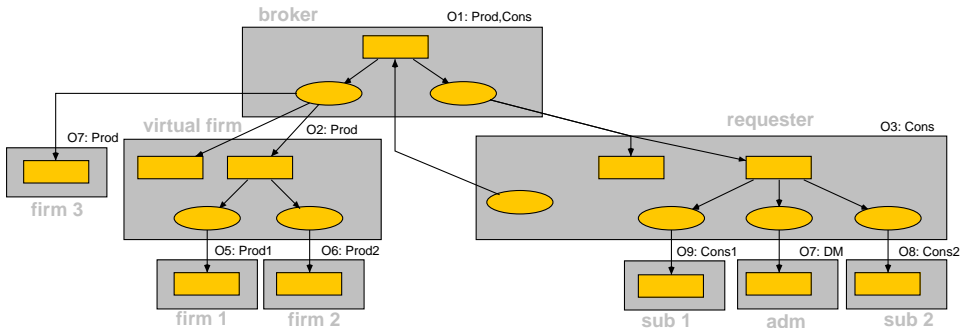
Agent Network

Static Aspects: Position Network, Roles, AIP



Interface Description

Static Aspects: Position Network, Roles, AIP

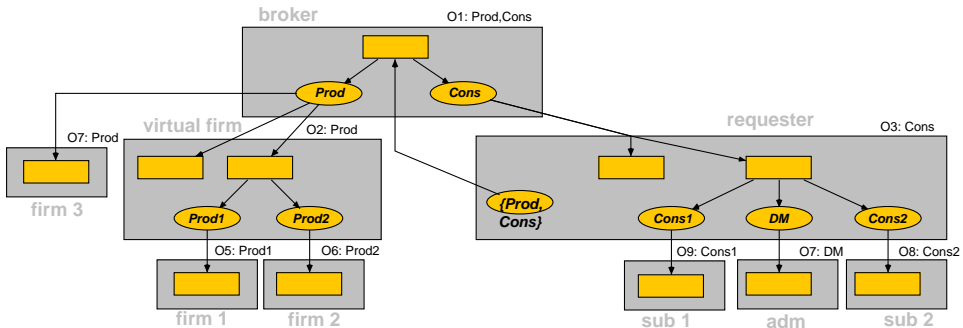


Petri Net

→ place = (sub)-task

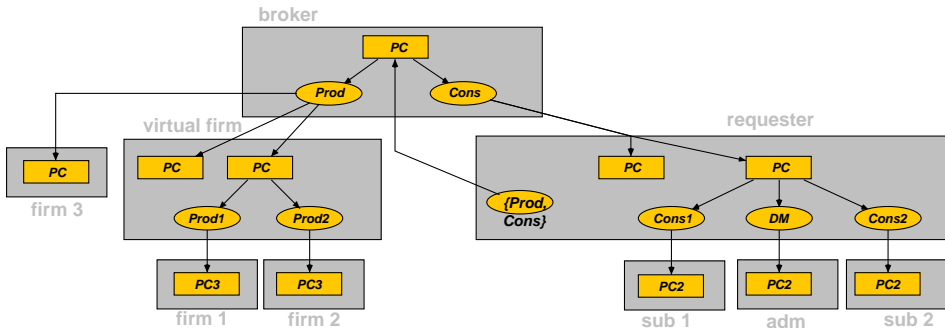
→ transition = delegation and/or refinement

Static Aspects: Position Network, Roles, AIP



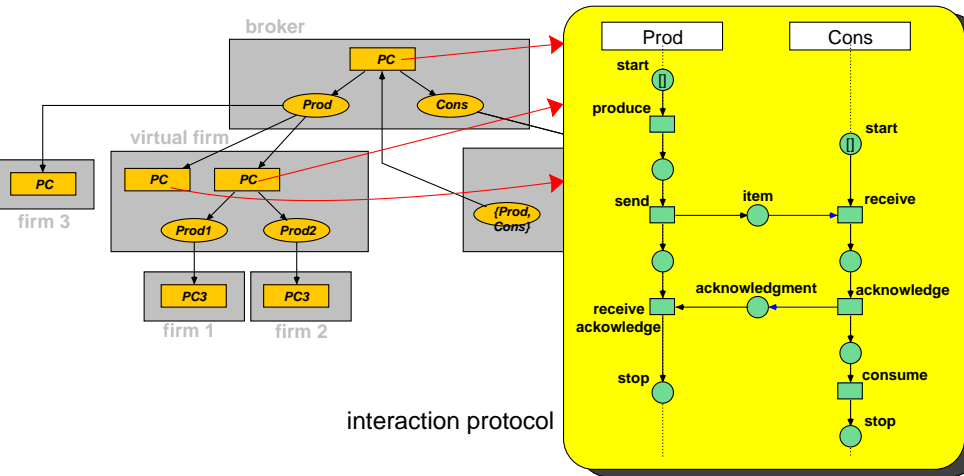
Roles

Static Aspects: Position Network, Roles, AIP

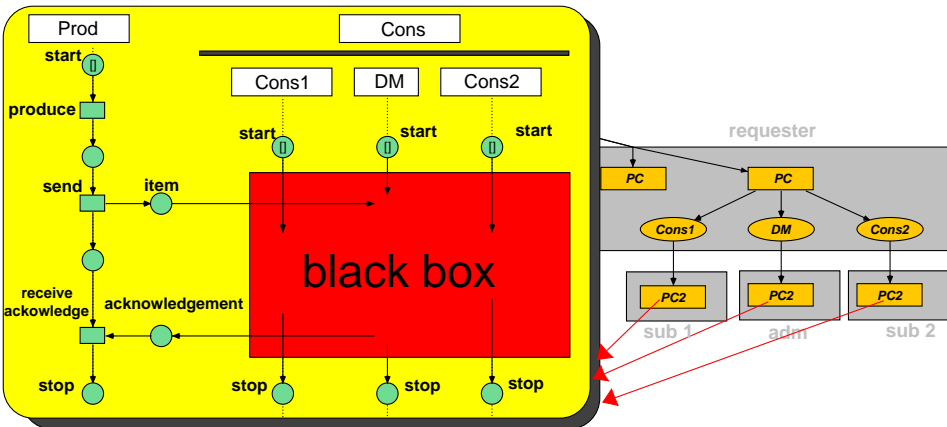


Interaction Protocols

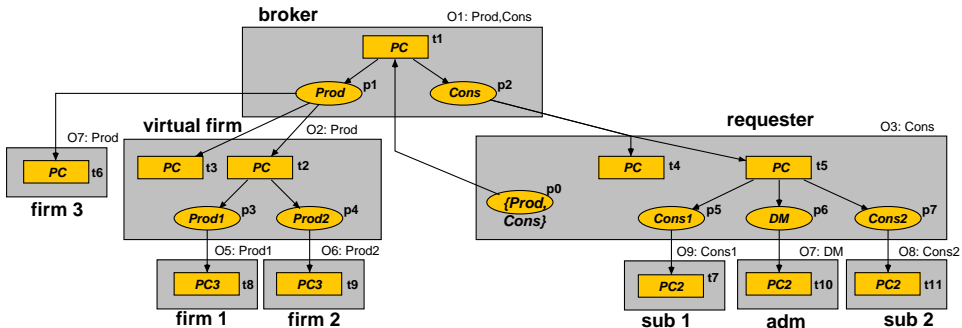
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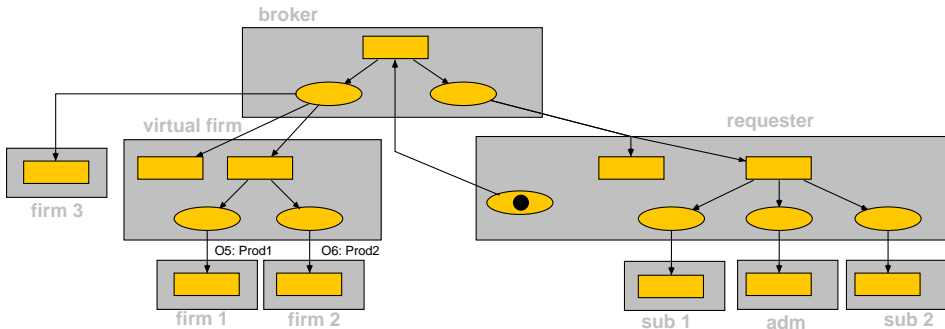
Static Aspects: Position Network, Roles, AIP



This is the static model structure.
What about the Petri Net dynamics?

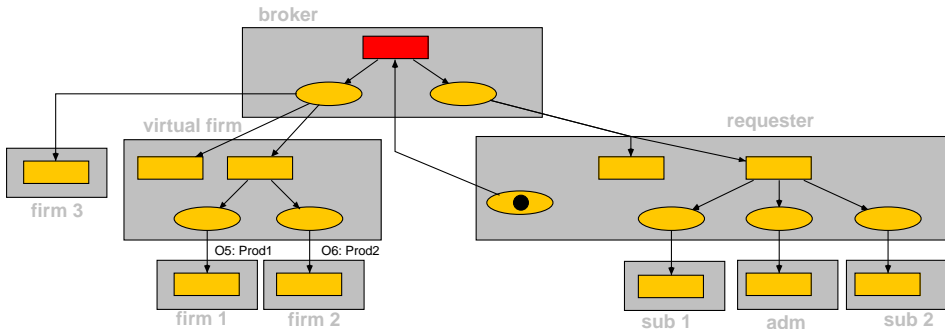
Dynamic Aspects: Teamformation

Petri Net Token Game = Team Formation



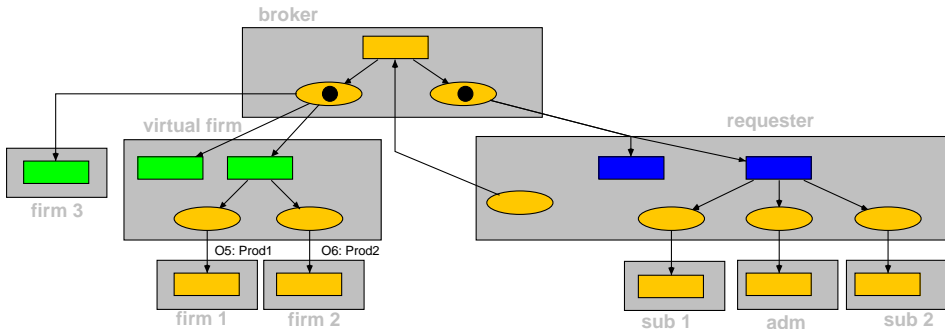
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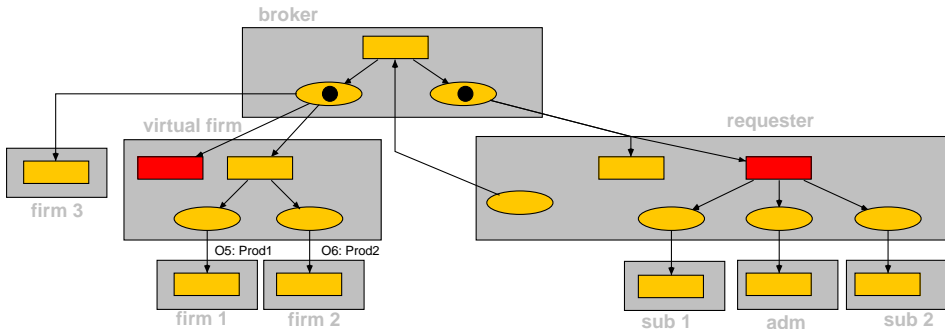
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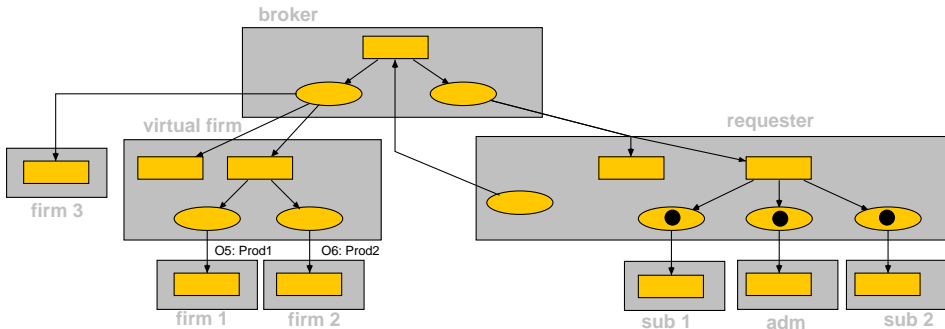
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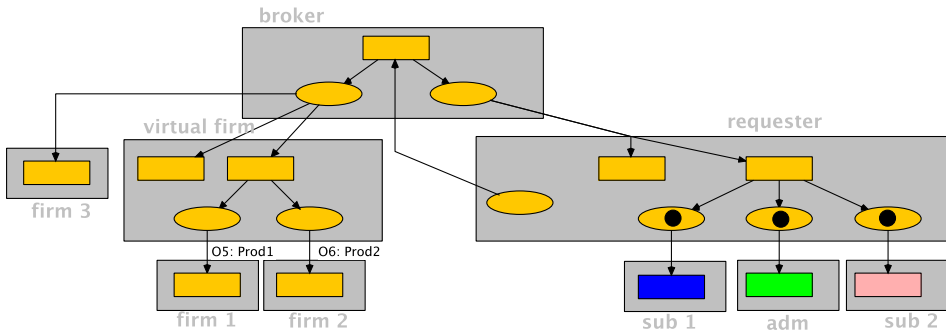
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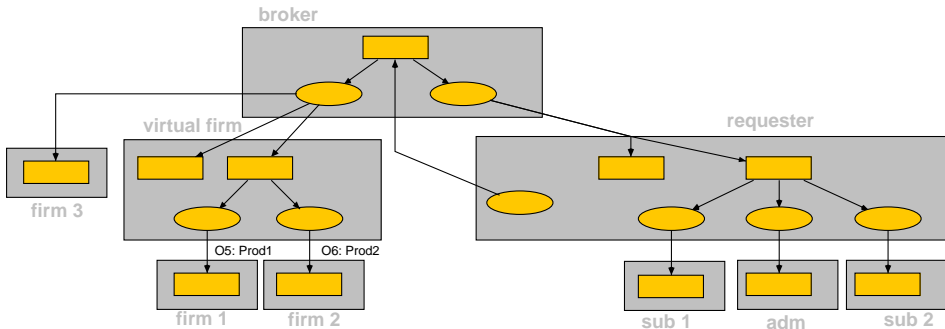
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Exploiting Petri Net Theory

Definition

An organisation net N is **sound** if each initial task can be performed via delegation.

This can easily expressed as a Petri net property:

Definition

- 1 A marking m is **processible** if the net can be emptied: $\mathbf{0} \in RS(m)$.
- 2 The net N is **processible** if **all** markings m are.

Problem: To prove processibility for N infinitely many markings m have to be considered.

Fortunately, this property can be expressed in terms of the net topology:

Theorem

A net N is processible iff

- (i) each place is reachable via a path from a initial place and*
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2 Mulan4Sonar

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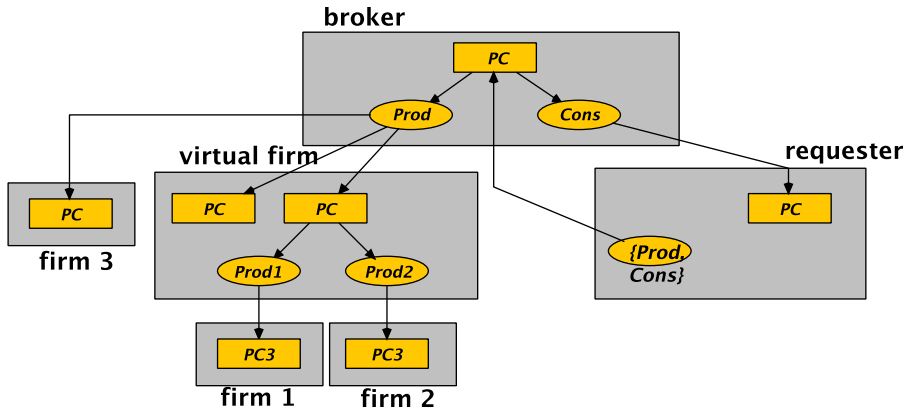
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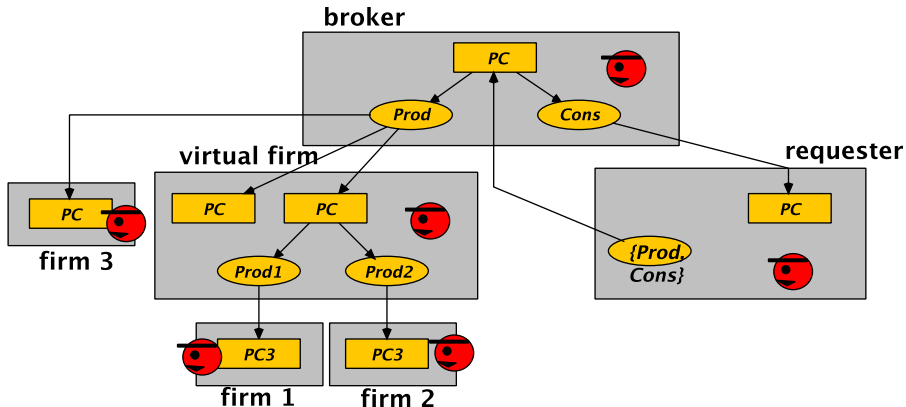
The Mulan4Sonar Middleware

Represent a SONAR-Model as a MAS:



The Mulan4Sonar Middleware

Represent a SONAR-Model as a MAS:



SONAR-Modell \mapsto MAS



Sonar Model

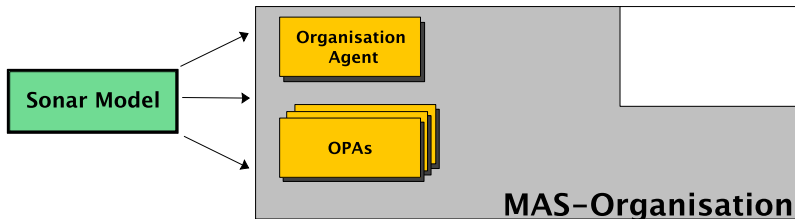
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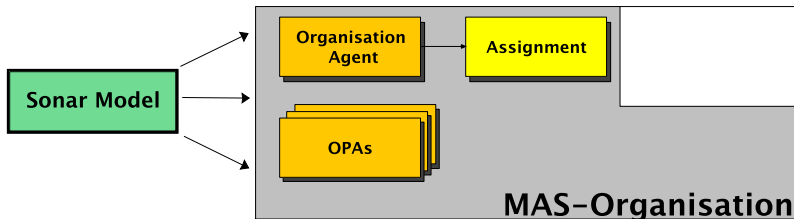
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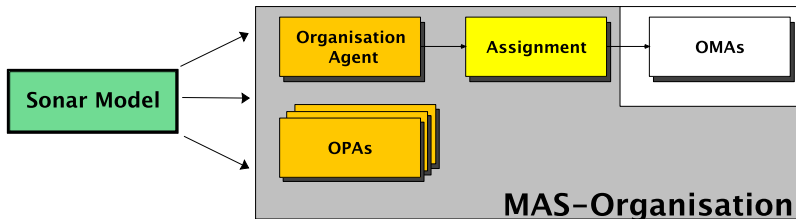
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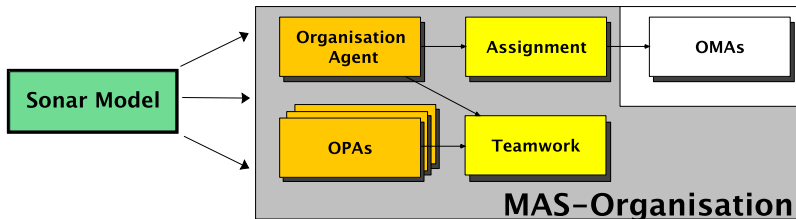
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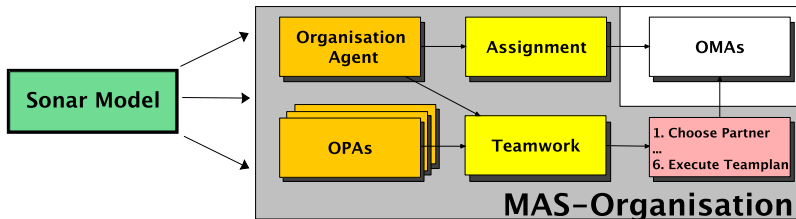
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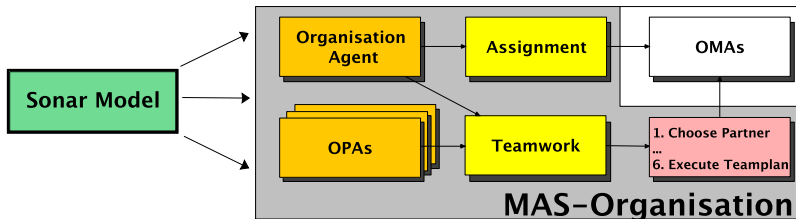
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Deployment of SONAR-Models

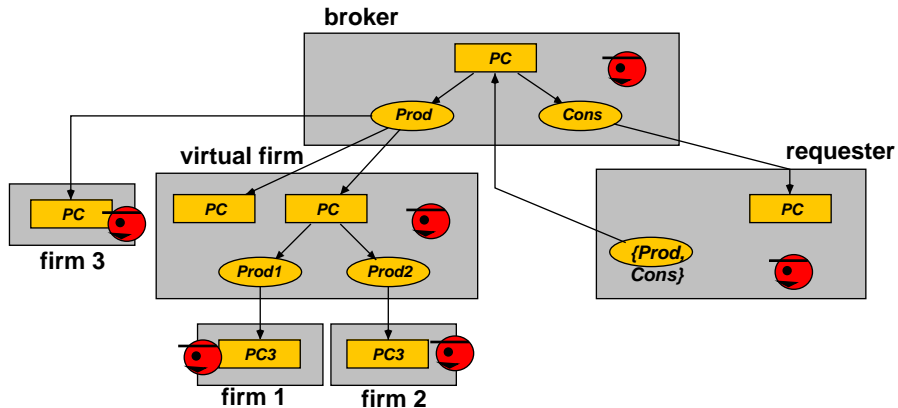
SONAR-Modell \mapsto MAS



- Organisation Agent
- Organisation Position Agent (OPA)
- Organisation Member Agent (OMA)

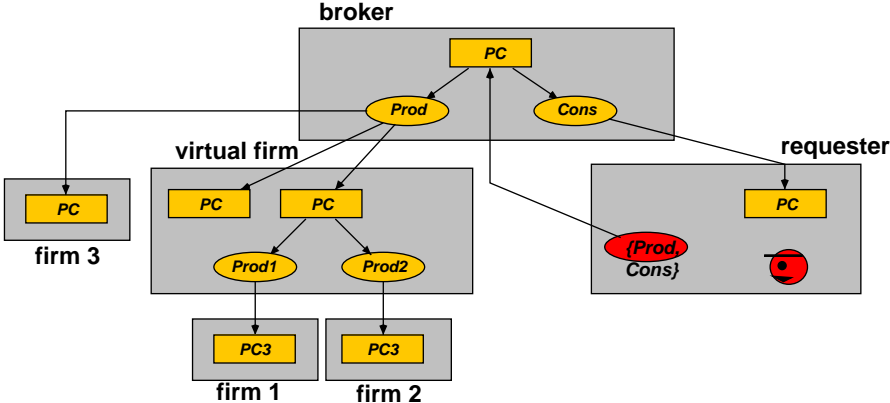
Example: Team Formation

Team Formation is the first of six teamwork phases.



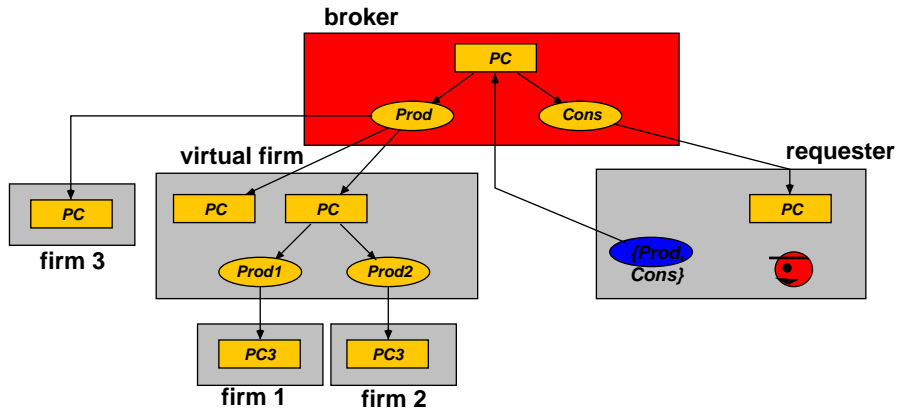
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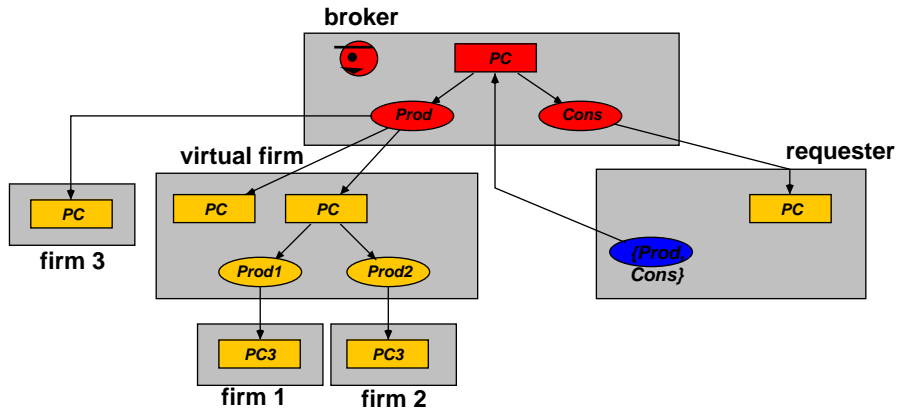
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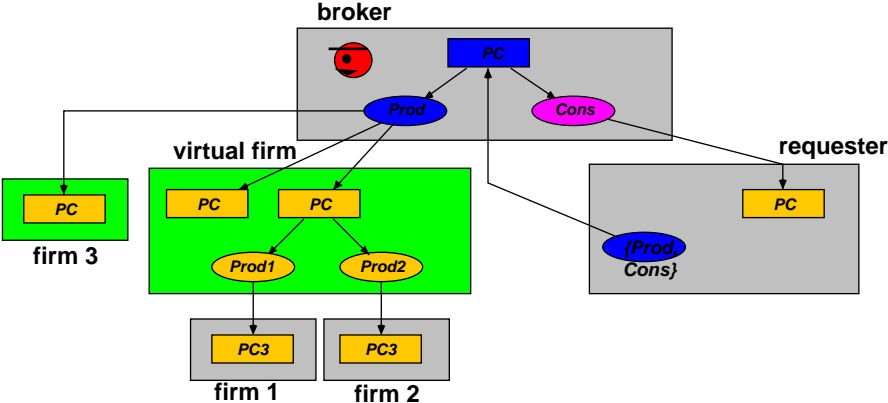
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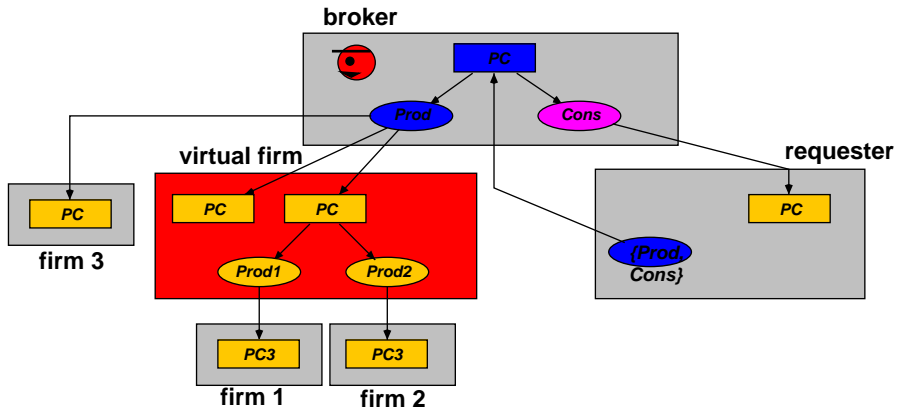
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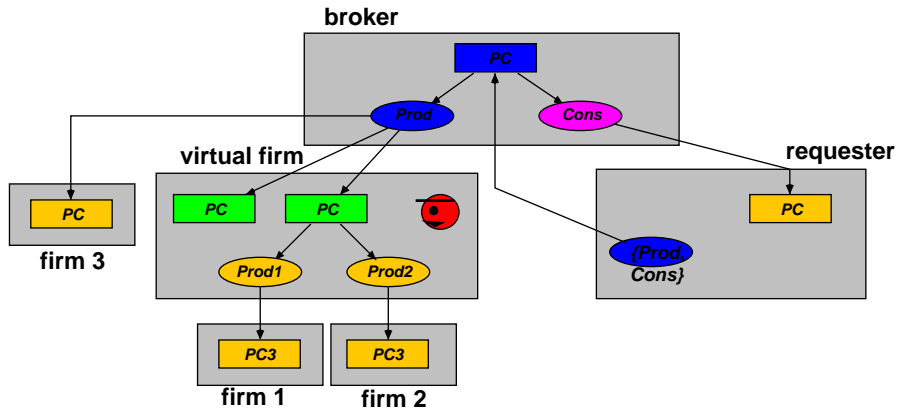
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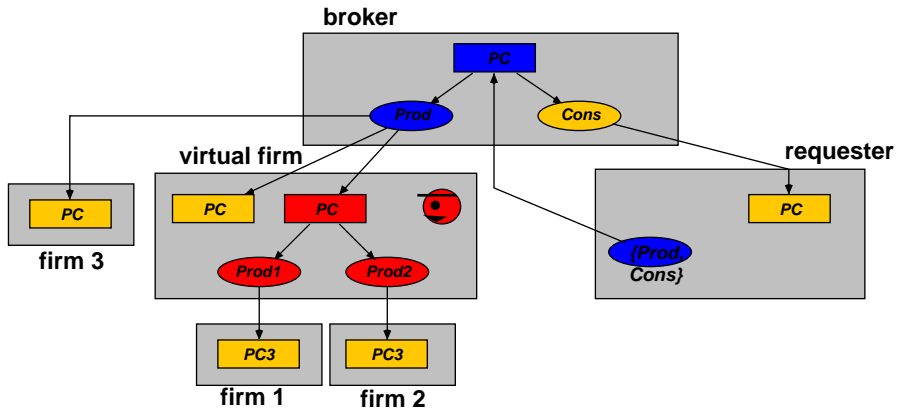
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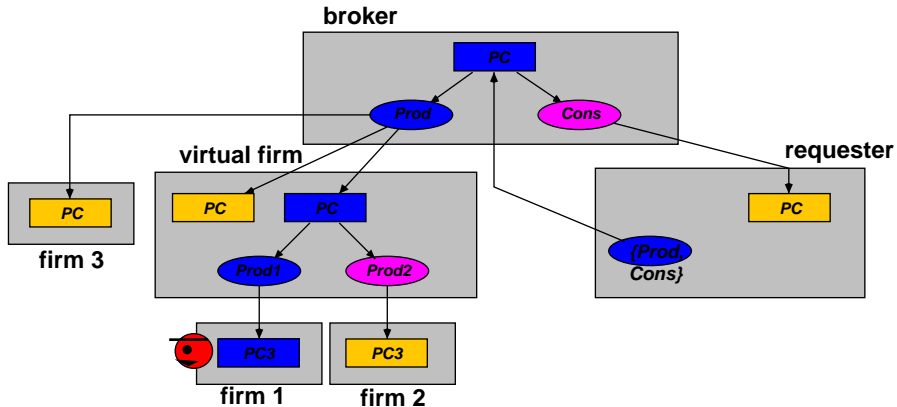
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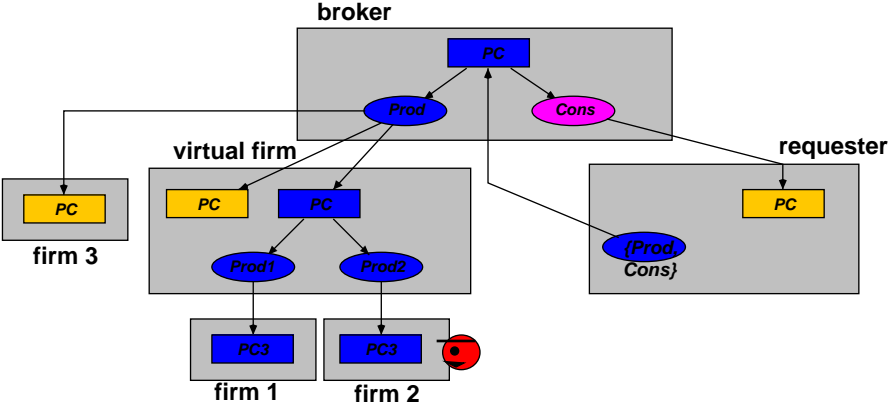
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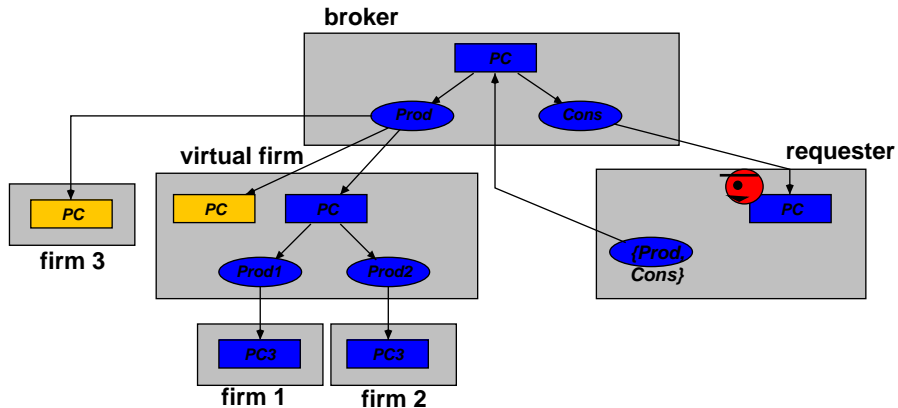
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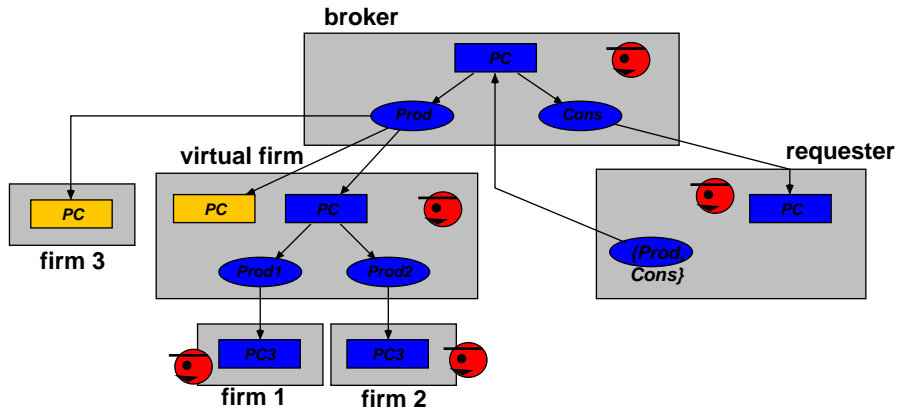
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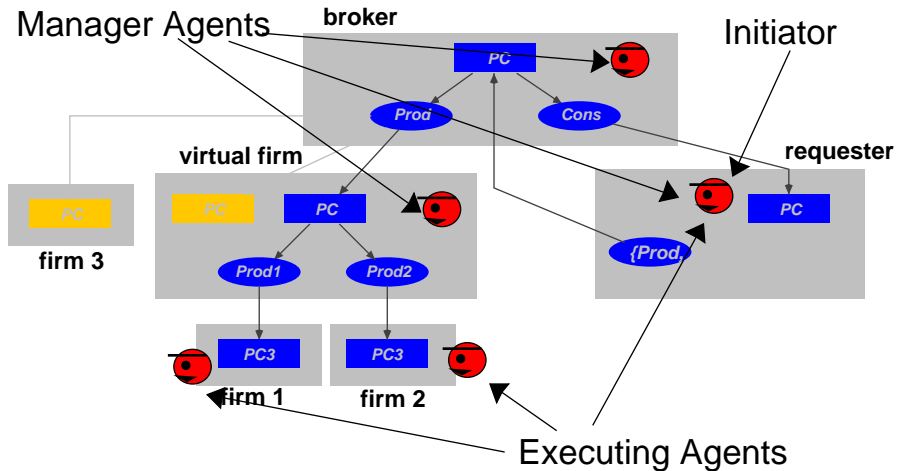
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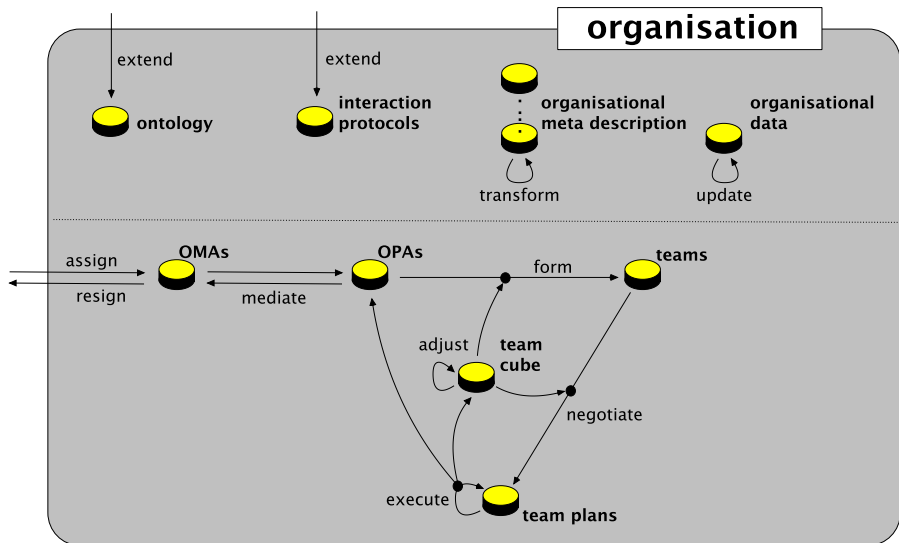
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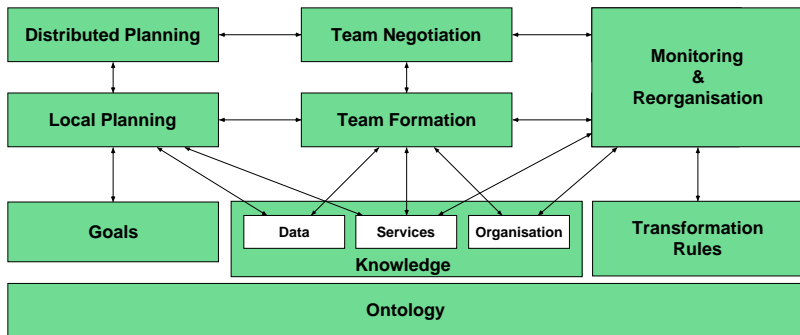
Generic Mulan4Sonar-Architecture: Organisation

Generic Organisational Agent:



Generic Mulan4Sonar-Architecture: OPA

Generic Organisational Position Agent (OPA):



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Middleware: Design Objectives

- 1 Rapid development. Need for a specification language that inherently supports powerful high-level features like pattern matching and synchronisation patterns.
- 2 Small gap between the specification and implementation. Ideally, middleware specifications are directly executable.
- 3 Well established analysis techniques to study the prototype's behaviour.
- 4 As close as possible to the original SONAR model.
- 5 Automatic generation of the middleware specifications from the SONAR model.
- 6 Easy transfer of the prototype into an agent programming language.

Compilation into Mulan4Sonar

MULAN4SONAR: From a SONAR-model we compile a high-level Petri net, namely a reference net, that implements the organisation.

Main benefits

- 1 The translation result is very close to the original specification, since the prototype directly incorporates the main Petri net structure of the SONAR-model;
- 2 The prototype is immediately functional as reference nets are directly executable using the open-source Petri net simulator RENEW.
- 3 Various well-supported analysis techniques for Petri nets: model-checking, structural reduction, linear algebraic approaches, etc.
- 4 We can easily integrate the prototype into MULAN – our MAS framework based on Java and reference nets.

The SONAR/OREDI compiler is implemented as a RENEW-plugin.

It is part of the P*AOSE approach: <http://www.paose.net/>

The Mulan4Sonar Prototype

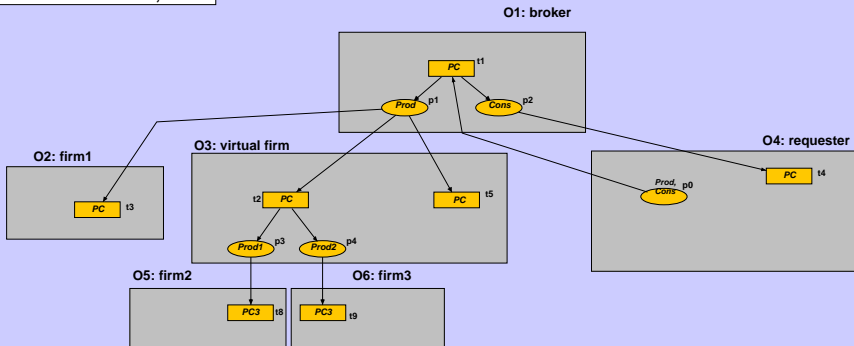
Support the six phases of SONAR-Teamwork in MULAN4SONAR:

- 1 Select the team agents.
- 2 Generate the team as an object of discourse.
- 3 Announce the team among the team agents.
- 4 Recursively process partial plans.
The executing team agents construct partial local plans.
These partial plans are recursively processed via negotiation by the ancestors in the team tree, resulting in a global plan.
- 5 Localise global team plan by the executing team agents.
- 6 Instantiate a team interaction protocol and starts the execution.

A Mulan4Sonar Example

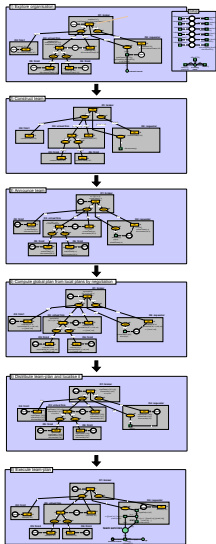
Compiler input: The following SONAR model

SONAR-model, n=1



A Mulan4Sonar Example

Compiler output: MULAN4SONAR middleware = 6 Petri Net modules

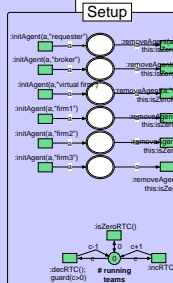
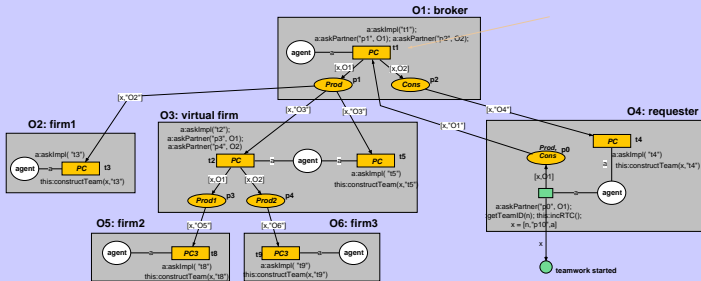


- 1 Select the team agents.
- 2 Generate the team.
- 3 Announce the team.
- 4 Negotiate: Recursively process partial plans.
- 5 Localise global team plan.
- 6 Instantiate a team interaction protocol.

6 Petri Net modules = 6 teamwork phases

A Mulan4Sonar Example

1) Explore organisation



2) Construct team

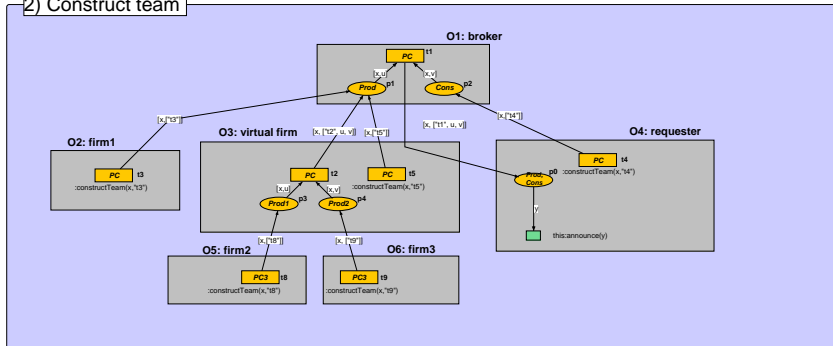


O1: broker

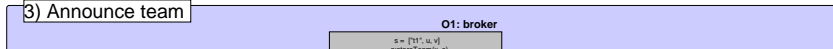
A Mulan4Sonar Example



2) Construct team

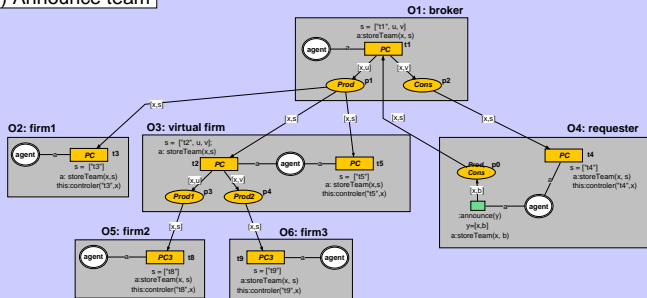


3) Announce team



A Mulan4Sonar Example

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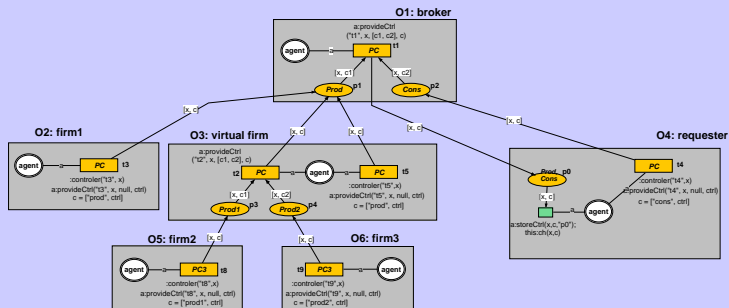


4) Compute global plan from local plans by negotiation

O1: broker
a:provideCtrl

A Mulan4Sonar Example

4) Compute global plan from local plans by negotiation



5) Distribute team-plan and localise it

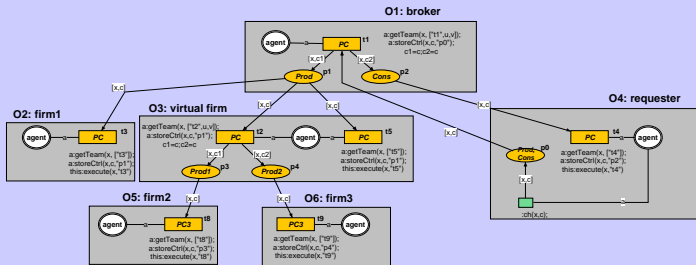
O1: broker

A Mulan4Sonar Example

c = [prod1, cny]

c = [prod2, cny]

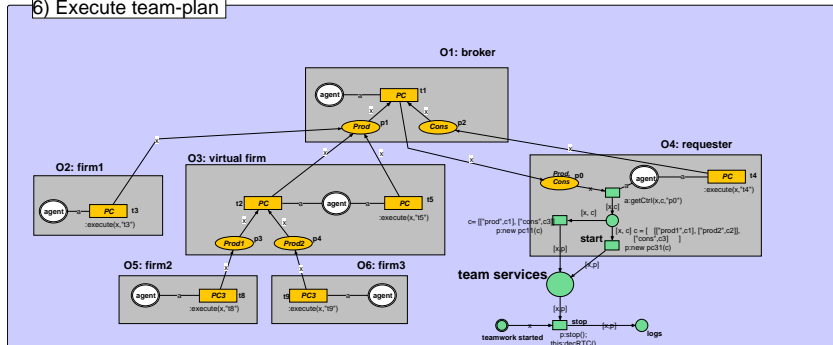
5) Distribute team-plan and localise it



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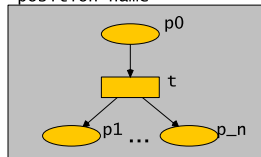
6) Execute team-plan



Compilation as Graph Transformation

Example: One graph transformation rule for phase 1:

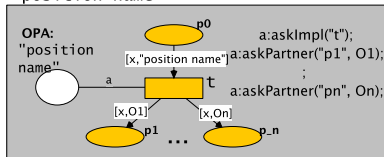
"position name"



Sonar Model



"position name"



Prototype

- add the place *OPA* which contains the position agent
- ask *OPA* to choose among its internal implementations for the input place via channel `a:askImpl(...)`
- ask *OPA* to choose delegation partners for each output place via channel `a:askPartner(...)`

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- Dynamic Aspects: Teamwork
- Theoretical Aspects

2 Mulan4Sonar

- Deployment of SONAR-Models
- The Organisation Agent
- The Position Agent

3 The Sonar/Oredi Compiler

- Middleware: Design Objectives
- The Mulan4Sonar Prototype
- Compilation as Graph Transformation

4 Conclusion

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